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Atsushi Ishikawa
Kanazawa Gakuin University
Shouji Fujimoto
Kanazawa Gakuin University
Tsutomu Watanabe
The University of Tokyo
Takayuki Mizuno
University of Tsukuba

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The Emergence of Different Tail Exponents in the Distributions of Firm Size Variables

Atushi Ishikawa^a, Shouji Fujimoto^a, Tsutomu Watanabe^b, Takayuki Mizuno^c

^a*Department of Informatics and Business, Faculty of Business Administration and Information Science, Kanazawa Gakuin University, 10 Sue, Kanazawa, Ishikawa 920-1392, Japan*

^b*Graduate School of Economics, University of Tokyo, 7-3-1 Hongo, Bunkyo-ku, Tokyo 113-0033, Japan*

^c*Doctoral Program in Computer Science, Graduate School of Systems and Information Engineering, University of Tsukuba, 1-1-1 Tennodai, Tsukuba, Ibaraki 305-8573, Japan*

Abstract

We discuss a mechanism through which inversion symmetry (i.e., invariance of a joint probability density function under the exchange of variables) and Gibrat's law generate power-law distributions with different tail exponents. Using a dataset of firm size variables, that is, tangible fixed assets K , the number of workers L , and sales Y , we confirm that these variables have power-law tails with different exponents, and that inversion symmetry and Gibrat's law hold. Based on these findings, we argue that there exists a plane in the three dimensional space $(\log K, \log L, \log Y)$, with respect to which the joint probability density function for the three variables is invariant under the exchange of variables. We provide empirical evidence suggesting that this plane fits the data well, and argue that the plane can be interpreted as the Cobb-Douglas production function, which has been extensively used in various areas of economics since it was first introduced almost a century ago.

Keywords: econophysics, power law, Gibrat's law, inversion symmetry

1. Introduction

In various phase transitions, it is universally observed that physical quantities near critical points obey power laws. For instance, in magnetic substances, specific heat, magnetic dipole density, and magnetic susceptibility follow power laws of heat or magnetic flux. It is also known that the cluster-size distribution of the spin follows power laws. The renormalization group approach has been employed to confirm that power laws arise as critical phenomena of phase transitions [1].

Email address: ishikawa@kanazawa-gu.ac.jp (Atushi Ishikawa)

There is a wide range of evidence that power laws can also be observed with regard to economic phenomena. The pioneering work was Ref. [2], in which personal income in England was shown to follow a power-law distribution. More recently, power-law distributions have been found in a wide variety of economic data [3]–[17], and across a variety of countries around the world [18]–[22]. However, no consensus has emerged as to the mathematical mechanisms that explain the emergence of power laws in economic data (see, e.g., [23]–[26]), even though numerous models have been developed to describe how power laws are generated in the natural sciences.

Given this background, the present paper seeks to understand how power laws emerge in economic data. The strategy we adopt is to focus on the relationship among various regularities (or laws) observed in economic data, such as Gibrat’s law and inversion symmetry. This approach was first proposed by Ref. [27] in the context of examining the dynamics of a single economic variable. Specifically, they first assume that a variable x obeys a power-law distribution for x greater than a threshold x_0 . The cumulative distribution function (CDF) of x , which is denoted by $P_{>}(x)$, is given by

$$P_{>}(x) \propto x^{-\mu} \quad \text{for } x > x_0 . \quad (1)$$

Next, they consider the joint probability density function (PDF) of x in time t and $t + 1$, which is denoted by $P_J(x(t), x(t + 1))$, and assume that

$$P_J(x(t), x(t + 1)) = P_J(x(t + 1), x(t)) , \quad (2)$$

which is referred to as time-reversal symmetry (or detailed balance) and denoted as $x(t + 1) \leftrightarrow x(t)$. It is also assumed that the distribution of the growth rate of x from t to $t + 1$, which is denoted by R , does not depend on the value of x at t when it exceeds the threshold x_0 ; that is,

$$Q(R|x(t)) = Q(R) \quad \text{for } x(t) > x_0 , \quad (3)$$

where the growth rate R is defined by $R = x(t + 1)/x(t)$. In other words, Gibrat’s law [29, 30] holds when $x(t)$ exceeds the threshold.

Time-reversal symmetry (2) and Gibrat’s law (3) for values exceeding a certain threshold imply that both $x(t + 1)$ and $x(t)$ have power-law tails [27, 28]. This property has been investigated in more detail by a number of studies. For example, Ref. [31] uses a numerical approach to show that x has a power-law tail when x is a random multiplicative process satisfying (2) and (3). On the other hand, Ref. [32] shows that power laws do not emerge if Gibrat’s law holds for all values of x rather than only for values exceeding a certain threshold. Similarly, there are some studies on random multiplicative processes, including [26, 8], that have shown that Gibrat’s law must be violated for some small values of x in order to obtain power laws. Also, some empirical studies, including [11, 12, 27, 28], confirm the emergence of power laws from time-reversal symmetry and Gibrat’s law using economic data such as personal income, land prices, and firm size variables. Moreover, Ref. [13] has shown that the distribution of the

rate of increase of stock prices, $Q(R = x(t + \tau)/x(t))$, where τ represents the time interval ranging from 1 minute to 1,000 minutes, follows a tent-shaped distribution once it is normalized by τ .

Somewhat surprisingly, most existing studies focus on a single variable and seek to understand how the power law of that single variable is generated. In this paper, we depart from this approach by looking at the interaction of multiple variables at a particular point in time (say, in a particular year) as a mechanism generating power laws. Specifically, we focus on the interaction of firm size variables at a particular point in time. Needless to say, different firm size variables of a particular firm at a particular point in time are correlated with each other. Specifically, Refs. [18, 33] have shown that firm sales and the number of workers follow power laws with different exponents and, more importantly, that there exists a nonlinear relationship between them. The presence of a nonlinear relationship among power-law variables with different tail exponents was also discussed by [34]–[36]. In this paper, we seek to investigate such nonlinear relationships in more detail with the aim of providing a new explanation of the origin of power-law distributions.

The rest of the paper is organized as follows. In Sec. 2, we provide a brief review of how power laws emerge from inversion symmetry and Gibrat’s law. Next, in Sec. 3, we apply the approach discussed in Sec. 2 to the data on tangible fixed assets K and sales Y to show the presence of inversion symmetry for the joint PDF of K and Y as well as the presence of a spatial version of Gibrat’s law. In Sec. 4, we then extend the discussion in Sec. 2 to three dimensional space. We show that there exists a plane in three dimensional space ($\log K$, $\log L$, $\log Y$), with respect to which the joint probability density function of the three variables is invariant under the exchange of variables. The plane is given by $\log Y = \alpha \log K + \beta \log L + \log A$, where α , β and A are positive parameters. This functional form is referred to as the Cobb-Douglas production function by economists and has been extensively used in various areas of economics since it was first introduced by [37] almost a century ago. Finally, in Sec. 5, we summarize our findings and discuss some additional issues.

2. Quasi-Inversion Symmetry

In this section, we explain how power laws emerge from inversion symmetry and Gibrat’s law, closely following the model of Refs. [11, 12]. Let us begin by defining two random variables u and v and assuming that the joint PDF of u and v , which is denoted by $P_J(u, v)$, is invariant under the exchange of variables. Specifically, it is assumed that the following equation holds:

$$P_J(u, v) = P_J\left(\left(\frac{v}{a}\right)^{1/\theta}, au^\theta\right), \quad (4)$$

where a and θ are parameters. We denote such invertibility as $v \leftrightarrow au^\theta$ and, following [11, 12], refer to (4) as quasi-inversion symmetry following Refs. [11, 12]. Note that this is an extension of time-reversal symmetry (2), which is

obtained if $u = x(t)$, $v = x(t+1)$, and $a = \theta = 1$ are substituted into (4). Next, let us define a new variable R by $R = v/(au^\theta)$ and assume that the conditional distribution $Q(R|u)$ does not depend on the value of u as long as u exceeds size threshold \bar{u} ; that is,

$$Q(R|u) = Q(R) \quad \text{for } u > \bar{u} . \quad (5)$$

In other words, Gibrat's law holds only when u exceeds \bar{u} .

It can be shown that quasi-inversion symmetry (4) and Gibrat's law with the lower bound (5) lead to power laws for u and v :

$$P_{>}(u) \propto u^{-\mu_u} \quad \text{for } u > \bar{u} , \quad (6)$$

$$P_{>}(v) \propto v^{-\mu_v} \quad \text{for } v > \bar{v} , \quad (7)$$

where μ_u and μ_v represent the power-law exponents for u and v . More importantly, it can be shown that μ_u and μ_v are related through $\mu_u = \theta\mu_v$.

Let us give a sketch of how these results are obtained. On the one hand, from the relation $P_J(u, R) du dR = P_J(u, v) du dv$, the following equations are obtained:

$$P_J(u, R) = au^\theta P_J(u, v) \quad (8)$$

$$= R^{-1}v P_J(u, v)$$

$$= R^{-1}v P_J\left(\left(\frac{v}{a}\right)^{1/\theta}, au^\theta\right) , \quad (9)$$

where (4) is used to obtain (9). On the other hand, by exchanging variables using $v \leftrightarrow au^\theta$, we can rewrite (8) as

$$P_J\left(\left(\frac{v}{a}\right)^{1/\theta}, R^{-1}\right) = v P_J\left(\left(\frac{v}{a}\right)^{1/\theta}, au^\theta\right) . \quad (10)$$

Combining (9) and (10) leads to

$$P_J(u, R) = R^{-1} P_J\left(\left(\frac{v}{a}\right)^{1/\theta}, R^{-1}\right) . \quad (11)$$

From the definition of the conditional probability $Q(R|u) = P_J(u, R)/P(u)$, (11) is rewritten as

$$\frac{P(u)}{P((v/a)^{1/\theta})} = \frac{1}{R} \frac{Q(R^{-1} | (v/a)^{1/\theta})}{Q(R | u)} = \frac{1}{R} \frac{Q(R^{-1})}{Q(R)} , \quad (12)$$

where Gibrat's law (5) is used to obtain (12). The final term of (12) is a function only of R and it is denoted by $G(R)$. Thus, we obtain

$$P(u) = G(R)P(R^{1/\theta}u) . \quad (13)$$

We approximate the right-hand side of (13) for R around 1 (namely, $R = 1 + \epsilon$ where $\epsilon \ll 1$) to obtain a differential equation of the form

$$G'(1)\theta P(u) + uP'(u) = 0, \quad (14)$$

where $G'(\cdot)$ is the derivative of $G(\cdot)$ with respect to R and $P'(\cdot)$ is the derivative of $P(\cdot)$ with respect to u . The unique solution to this differential equation is given by

$$P(u) = C_T u^{-G'(1)\theta}. \quad (15)$$

Note that, as shown by [27, 28], (15) continues to be a general solution to (13) even if R deviates substantially from $R = 1$, as long as $Q(R)$ satisfies $Q(R) = R^{-G'(1)-1}Q(R^{-1})$. This condition for $Q(R)$ has been shown to be satisfied for various economic data, including firm size variables and personal income [27, 28].

Next, we characterize $P(v)$. Using (15) and the relation $P(u) du = P(v) dv$, we obtain

$$P(v) = P(u) \frac{du}{dv} = \frac{C_T a^{G'(1)-1/\theta}}{\theta} v^{-G'(1)+1/\theta-1}. \quad (16)$$

Eqs. (15) and (16) show that quasi-inversion symmetry and Gibrat's law generate power-law distributions for u and v with different power-law exponents. Moreover, by comparing (15) and (16) with (6) and (7), we see that the two power-law exponents are related as follows:

$$\mu_u = \theta \mu_v. \quad (17)$$

That this relationship holds in practice is shown by Refs. [11, 12] using land price data. Specifically, investigating land price distributions in year t and year $t+1$, Refs. [11, 12] shows that $\mu_{x(t)} = \theta \mu_{x(t+1)}$ holds, where $x(t)$ and $x(t+1)$ are land prices in year t and $t+1$, $\mu_{x(t)}$ and $\mu_{x(t+1)}$ are the estimated tail exponents for the two distributions, and θ is the parameter estimated from inversion symmetry for $P_J(x(t), x(t+1))$. Also note that a relationship between power-law exponents that is similar to (17) has been derived by Ref. [38], although their approach differs from ours in that they focus on the part of a firm size distribution that is log-normally distributed rather than the power-law part of the distribution.

3. Example of Quasi-Inversion Symmetry

In this section, we examine empirically whether power laws are actually generated from inversion symmetry and Gibrat's law. The dataset we use is from ORBIS, a database compiled by Bureau van Dijk [39] that contains information on firms around the world. In this section, we use firm sales Y and tangible fixed assets K to examine a two-variable system (K, Y) .

We start by showing that K and Y follow power-law distributions for values exceeding certain size thresholds, which are given by \bar{K} , \bar{Y} . That is,

$$P_{>}(K) \propto K^{-\mu_K} \quad \text{for } K > \bar{K}, \quad (18)$$

$$P_{>}(Y) \propto Y^{-\mu_Y} \quad \text{for } Y > \bar{Y}, \quad (19)$$

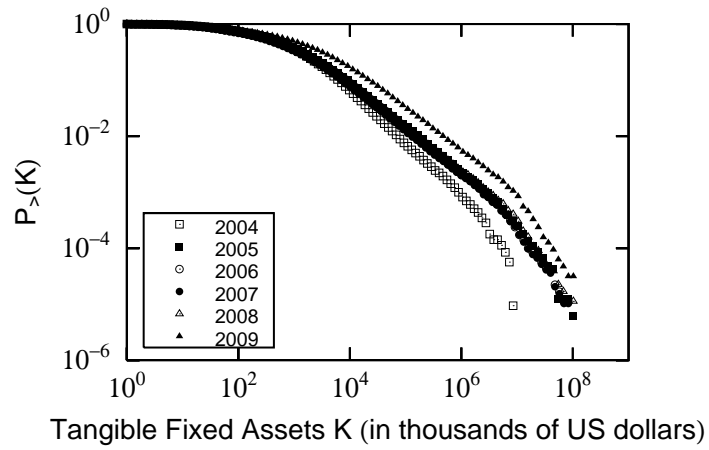


Figure 1: Distributions of tangible fixed assets K for Japanese firms in 2004 to 2009. The number of firms changes across years but on average is 601,211.

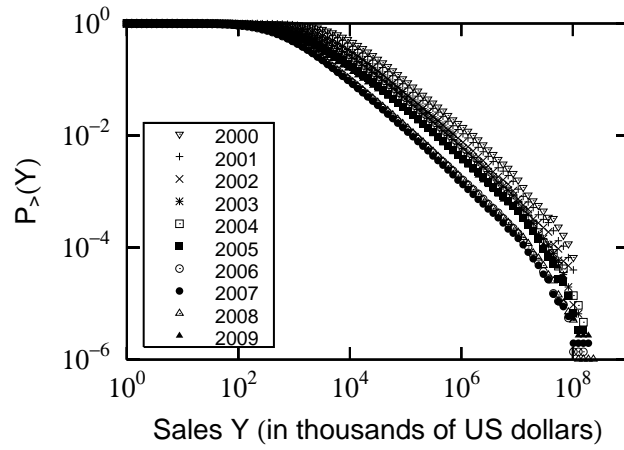


Figure 2: Distributions of sales Y for Japanese firms in 2000 to 2009. The number of firms changes across years but on average is 399,982.

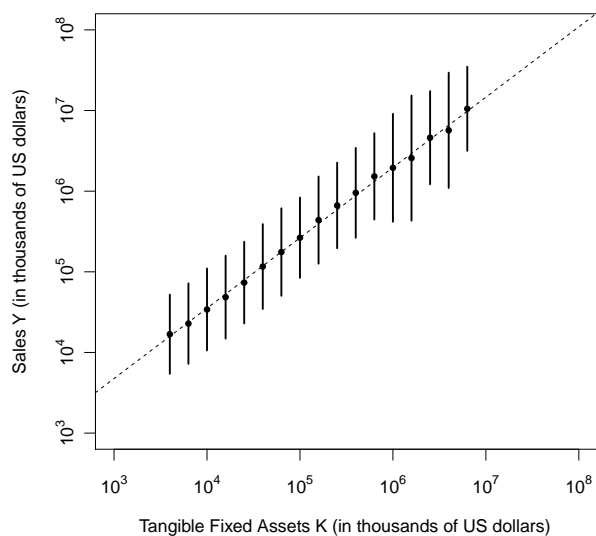


Figure 3: Relationship between tangible fixed assets K and sales Y for Japanese firms in 2008. The horizontal axis shows the values of K for the tail part of its distribution (i.e., the range in which K follows a power-law distribution), while the vertical axis shows the values of Y . The dots and the bars represent, respectively, the mean and the standard deviation of $\log Y$ for each bin of K , which is of the same size in log. We fit a line, $\log Y = \theta_{KY} \log K + \log a_{KY}$, to the dots, which is indicated by the dashed line.

Figs. 1 and 2 show the CDFs of K and Y for Japanese firms in various years. We see that the K and Y for each year have a power-law tail for values exceeding a certain size threshold. Next, we show that $P_J(K, Y)$ is invariant under the exchange of variables,

$$P_J(K, Y) = P_J \left(\left(\frac{Y}{a_{KY}} \right)^{1/\theta_{KY}}, a_{KY} K^{\theta_{KY}} \right), \quad (20)$$

which is denoted by $Y \leftrightarrow a_{KY} K^{\theta_{KY}}$. Fig. 3 shows the relationship between K and Y for Japanese firms in 2008. The dashed line represents the line $\log Y = \theta_{KY} \log K + \log a_{KY}$ with respect to which quasi-inversion symmetry holds. This line is estimated as follows.

Step 1: The range in which K follows a power-law distribution is identified by the method proposed by Ref. [40], which is a modified version of the method advocated by Ref. [41]. As shown in Figs. 1 and 2, the right-end part of each distribution decays quicker than the rest of the distribution due to the limited number of observations. Such a finite-size effect is not present in small datasets, so it is not regarded as important in Ref. [41]. However, in large datasets, such as the one used in this paper, distributions are seriously affected by the finite-size effect, so that a simple application of the method proposed by Ref. [41] could lead to a failure to correctly detect the range in which K follows a power-law distribution. To avoid this, Ref. [40] proposes to “thin out” observations before applying the procedure by Ref. [41]. We adopt this method to detect \bar{K} . We employ the same procedure for the distribution of Y to detect \bar{Y} .

Step 2: The power-law range of K is divided into bins which are of the same size in log, and the geometric average of Y is calculated for the observations belonging to each bin, which is shown by the round dots in Fig. 3. We then run a least squares regression to fit the line $\log Y = \theta_{KY} \log K + \log a_{KY}$ to the dots. A similar method was adopted in Refs. [18], [33]. Note that we apply the least squares method not to individual observations but to the dots so as to give an equal weight to the right and left ends of the distribution. Finally, we conduct a Kolmogorov-Smirnov test to confirm that (20) holds with respect to the estimated line.

Next, let us consider the ratio between K and Y , which is denoted by $R_{KY} = Y/(a_{KY} K^{\theta_{KY}})$. Fig. 4 shows the PDF of R_{KY} conditional on K , which is denoted by $Q(R_{KY} | K)$. We see that the PDF of R_{KY} does not depend on K , when K exceeds the size threshold \bar{K} . That is,

$$Q(R_{KY} | K) = Q(R_{KY}) \quad \text{for } K > \bar{K}. \quad (21)$$

Finally, we check condition (17). We estimate μ_K/μ_Y and θ_{KY} for twelve countries. The result is shown in Fig. 5. We fit a line to the data and obtain $\mu_K/(\mu_Y \theta_{KY}) = 0.94 \pm 0.03$, indicating that the data are almost consistent with $\mu_K = \theta_{KY} \mu_Y$, although μ_K is slightly smaller than $\theta_{KY} \mu_Y$.

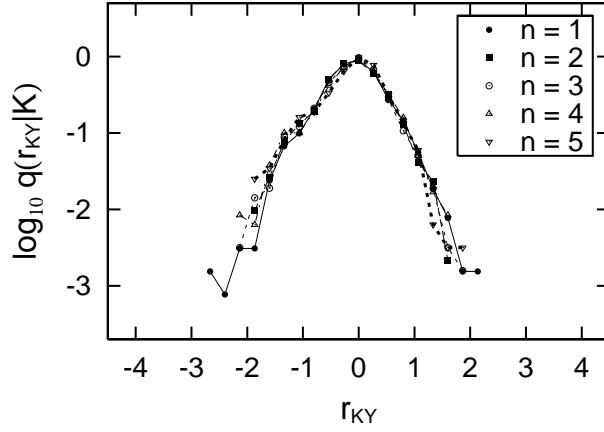


Figure 4: PDFs of $r_{KY} (\equiv \log R_{KY})$ conditional on K . The range of K is divided into logarithmically equal size bins, which are given by $K \in [10^{4+0.2(n-1)}, 10^{4+0.2n})$, $n = 1, 2, \dots, 5$.

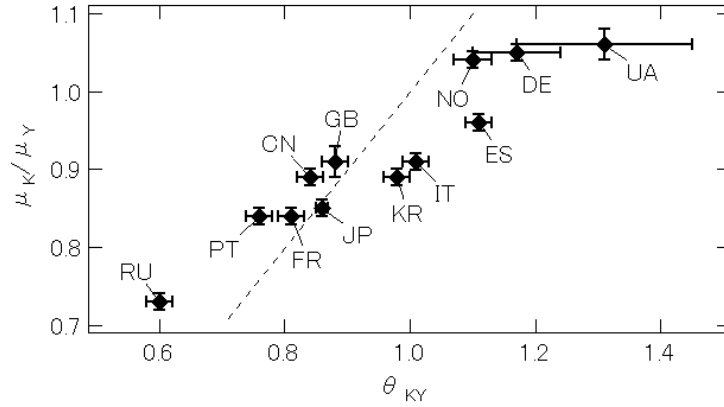


Figure 5: Relationship between μ_K/μ_Y and θ_{KY} in 2006 for twelve countries, namely Japan (JP, the number of observations is 723,109), France (FR, 887,142), Spain (ES, 718,729), Italy (IT, 611,988), Russian Federation (RU, 548,086), United Kingdom (GB, 342,370), Portugal (PT, 280,941), Korea (KR, 134,450), China (CN, 247,318), Ukraine (UA, 252,144), Norway (NO, 162,983) and Germany (DE, 213,017). The dashed line represents $\mu_K = \theta_{KY} \mu_Y$.

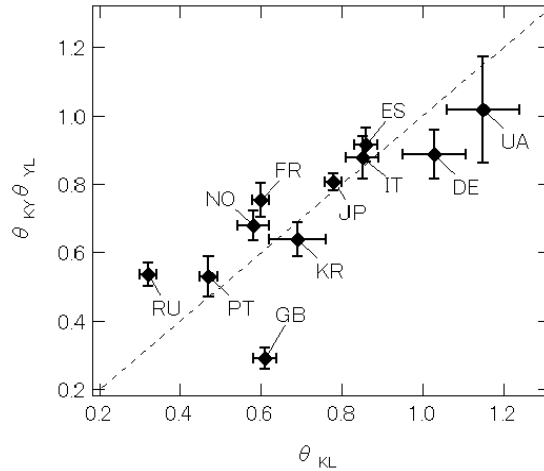


Figure 6: Relationship between θ_{KL} and $\theta_{KY}\theta_{YL}$ for eleven countries in 2008. The dashed line represents $\theta_{KL} = \theta_{KY}\theta_{YL}$.

4. Inversion Symmetry in Three-Dimensional Space

In the previous section, we observed inversion symmetry in the $(\log K, \log Y)$ plane and showed that inversion symmetry and Gibrat's law lead to power laws for the distributions of K and Y . We apply the same analysis to the other sets of variables, that is $(\log Y, \log L)$ and $(\log K, \log L)$, to find that the three θ 's estimated by regressions (i.e., θ_{KL}, θ_{KY} , and θ_{YL}) are related to each other through $\theta_{KL} \simeq \theta_{KY}\theta_{YL}$, as shown in Fig. 6. This result suggests the presence of inversion symmetry and Gibrat's law in the three dimensional space $(\log K, \log L, \log Y)$. In this section, we extend the discussion in Sec. 2 to three dimensional space.

Consider a plane in the three dimensional space $(\log u_1, \log u_2, \log v)$, which is given by

$$\log v = \theta_1 \log u_1 + \theta_2 \log u_2 + \log A, \quad (22)$$

and assume that the joint PDF of the three variables, $P_J(u_1, u_2, v)$, is invertible in the sense that $v \leftrightarrow Au_1^{\theta_1}u_2^{\theta_2}$. Specifically, inversion symmetry in the three dimensional space is defined as

$$P_J(u_1, u_2, v) = P_J\left(\left(\frac{v}{Au_2^{\theta_2}}\right)^{1/\theta_1}, \left(\frac{v}{Au_1^{\theta_1}}\right)^{1/\theta_2}, Au_1^{\theta_1}u_2^{\theta_2}\right). \quad (23)$$

We also assume a three-dimensional version of Gibrat's law,

$$Q(R|u_1, u_2) = Q(R) \quad \text{for } u_1 > \bar{u}_1 \quad \text{and} \quad u_2 > \bar{u}_2, \quad (24)$$

where \bar{u}_1 and \bar{u}_2 represent the size thresholds of u_1 and u_2 , R is defined by $R = v/(Au_1^{\theta_1}u_2^{\theta_2})$, and $Q(R|u_1, u_2) = P_J(u_1, u_2, R)/P_J(u_1, u_2)$. Note that R

is closely related to what economists refer to as total factor productivity. We will come back to this issue later in the next section.

From (23) and (24), we obtain

$$P_J(u_1, u_2) = G(R)P_J(R^{1/\theta_1}u_1, R^{1/\theta_2}u_2), \quad (25)$$

which corresponds to (13) in Sec. 2. We expand (25) around $R = 1$ (namely, $R = 1 + \epsilon$ where $\epsilon \ll 1$) to obtain a differential equation. Under the assumption that u_1 and u_2 are mutually independent, the solution to the differential equation is given by

$$P_J(u_1, u_2) = C_T u_1^{-\mu_1-1} u_2^{-\mu_2-1}, \quad (26)$$

where μ_1 and μ_2 are positive parameters satisfying $\frac{\mu_1+1}{\theta_1} + \frac{\mu_2+1}{\theta_2} = G'(1)$. Note that μ_1 and μ_2 are the power-law exponents associated with u_1 and u_2 .

Turning to the PDF of v , the result obtained by Refs. [35, 36] implies that, given the assumption that u_1 and u_2 are mutually independent, the product of u_1 and u_2 also follows a power-law distribution, with its exponent given by $\min\{\mu_1/\theta_1, \mu_2/\theta_2\}$. Therefore, $P(v)$ is given by

$$P(v) \propto v^{-\mu_v-1}, \quad (27)$$

where

$$\mu_v = \min\{\mu_1/\theta_1, \mu_2/\theta_2\}. \quad (28)$$

Note that (28) corresponds to (17) in the two dimensional case.

We now proceed to the empirical investigation of inversion symmetry in three dimensional space. We first eliminate the high correlation between $\log K$ and $\log L$ by converting $(\log K, \log L)$ into $(\log Z_1, \log Z_2)$. The new variables $\log Z_1$ and $\log Z_2$ are defined as

$$\log Z_1 = \frac{\log L}{\sqrt{2}\sigma_{\log L}} + \frac{\log K}{\sqrt{2}\sigma_{\log K}}; \quad \log Z_2 = \frac{\log L}{\sqrt{2}\sigma_{\log L}} - \frac{\log K}{\sqrt{2}\sigma_{\log K}}, \quad (29)$$

where $\sigma_{\log K}$ and $\sigma_{\log L}$ are the standard deviations of $\log K$ and $\log L$, respectively. Note that, by construction, $\log Z_1$ and $\log Z_2$ are uncorrelated. We have confirmed that Z_1 and Z_2 follow power-law distributions for $Z_1 > \bar{Z}_1$ and $Z_2 > \bar{Z}_2$. Also, we have conducted a chi-squared test to confirm that Z_1 and Z_2 are mutually independent for $Z_1 > \bar{Z}_1$ and $Z_2 > \bar{Z}_2$. We then fit a plane, $\log Y = \theta_{Z_1 Y} \log Z_1 + \theta_{Z_2 Y} \log Z_2 + \log A$, to the observations for $Z_1 > \bar{Z}_1$ and $Z_2 > \bar{Z}_2$ to obtain estimates for $\theta_{Z_1 Y}$ and $\theta_{Z_2 Y}$. For Japanese firms in 2008, the estimate of $\theta_{Z_1 Y}$ turns out to be 0.38 with a standard error of 0.005, while the estimate of $\theta_{Z_2 Y}$ is 0.08 with a standard error of 0.01. We have confirmed the presence of inversion symmetry with respect to this estimated line (i.e., $Y \leftrightarrow AZ_1^{\theta_{Z_1 Y}} Z_2^{\theta_{Z_2 Y}}$) as well as the presence of Gibrat's law.

Next, we check whether condition (28) holds in the data. For Japanese firms in 2008, the estimate of the power-law exponent associated with Z_1 , which is denoted by μ_{Z_1} , is 0.38 with a standard error of 0.01, while the estimate of the power-law exponent for Z_2 , denoted by μ_{Z_2} , is 1.16 with a standard error of 0.01. Therefore, $\mu_{Z_1}/\theta_{Z_1 Y}$ is 0.99 and $\mu_{Z_2}/\theta_{Z_2 Y}$ is 14.5, so that

$\min\{\mu_{Z_1}/\theta_{Z_1Y}, \mu_{Z_2}/\theta_{Z_2Y}\} = 0.99 \pm 0.03$. In other words, the theoretical prediction is that the power-law exponent associated with Y should be 0.99. In fact, the estimate of the power-law exponent for Y turns out to be 0.95 with a standard error of 0.01, which is close to the theoretical prediction. Furthermore, we find inversion symmetry between $\log Z_1$ and $\log Y$ in two dimensional space, as shown in Fig. 7. It is important to note that the slope of the fitted line in Fig. 7 is 0.38 ± 0.003 , which is quite close to the estimate of θ_{Z_1Y} obtained in three dimensional space. We also confirm the presence of Gibrat's law in the $(\log Z_1, \log Y)$ space, as shown in Fig. 8. These two results indicate that the presence of inversion symmetry and Gibrat's law in two dimensional space is just a reflection of inversion symmetry and Gibrat's law in three dimensional space, as predicted by the theoretical considerations above.

The inversion symmetry in three dimensional space discussed in this section also has a meaning in terms of economics. To show this, we first note that inversion symmetry in the $(\log Z_1, \log Z_2, \log Y)$ space can be converted into inversion symmetry in the $(\log K, \log L, \log Y)$ space, with the axis of inversion symmetry given by

$$\log Y = \alpha \log K + \beta \log L + \log A, \quad (30)$$

where α and β are defined by

$$\alpha = \frac{\theta_{Z_1Y} - \theta_{Z_2Y}}{\sqrt{2}\sigma_{\log K}}; \quad \beta = \frac{\theta_{Z_1Y} + \theta_{Z_2Y}}{\sqrt{2}\sigma_{\log L}}. \quad (31)$$

We denote this inversion symmetry by $Y \leftrightarrow AK^\alpha L^\beta$. Eq. (30) is referred to as the Cobb-Douglas production function by economists and has been widely used in economics since it was first introduced in 1928 by Ref. [37]. Specifically, economists have been using the idea of production functions to describe the nonlinear relationship between output and inputs. At the firm-level, for example, the output of a firm, Y (e.g., measured in terms of sales), is a positive function of, e.g., the number of people working for the firm, L , and the number of machines it uses, K , as well as the productivity of the firm, A , that is, the efficiency with which these inputs are used. This relationship is referred to as a production function, and the most widely used functional form for production functions is the Cobb-Douglas form. Although there are a number of studies by economists, such as [42]–[44], seeking to provide a theoretical foundation for the Cobb-Douglas functional form, no consensus has yet been found. The discussion in this section provides a new theoretical foundation for the Cobb-Douglas form.

5. Conclusion

In this paper, we discussed the mechanism through which inversion symmetry and Gibrat's law generate power-law distributions with different tail exponents. Using a dataset containing firm size variables for firms in various

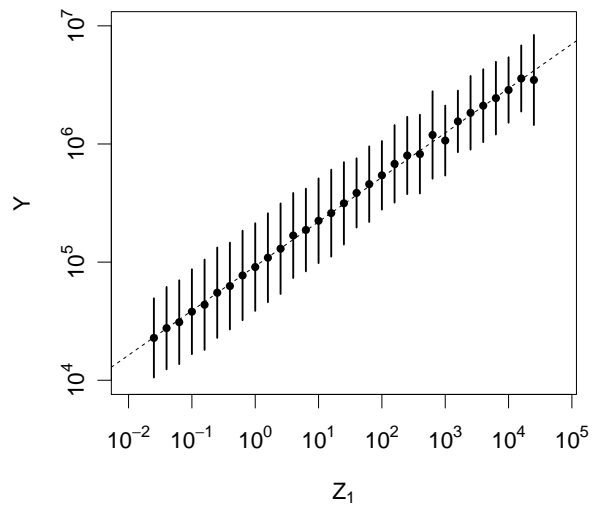


Figure 7: Relationship between Z_1 and Y for Japanese firms in 2008. The dots and the bars represent, respectively, the mean and the standard deviation of $\log Y$ for each bin of Z_1 , which is of the same size in log. We fit a line, $\log Y = \theta_{Z_1 Y} \log Z_1 + \log a_1$, to the data, which is indicated by the dashed line.

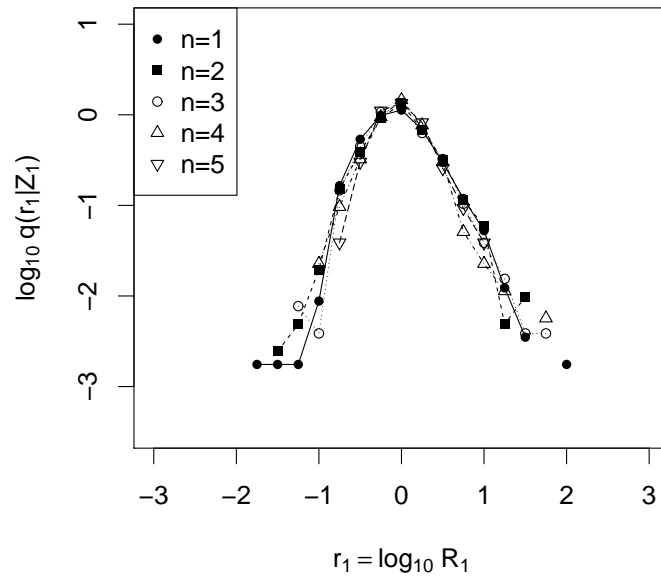


Figure 8: PDFs of r_1 conditional on Z_1 , where r_1 is defined as $r_1 \equiv \log[Y/(a_1 Z_1^{\theta Z_1^Y})]$. The range of Z_1 is divided into bins of the same size in log, which are given by $Z_1 \in [10^{0.5(n-1)}, 10^{0.5n})$, $n = 1, 2, \dots, 5$.

countries, that is, tangible fixed assets K , the number of workers L , and sales Y , we confirmed that they have power-law tails with different exponents. We also confirmed that inversion symmetry and Gibrat's law hold, and that the power law exponents for K , L , and Y satisfy the relationship implied by theory.

Based on these findings, we argue that there exists a plane in the three dimensional space $(\log K, \log L, \log Y)$, with respect to which the joint probability density function for the three variables is invariant under the exchange of variables. We provide empirical evidence that this plane fits the data well and argue that the plane can be interpreted as the Cobb-Douglas production function, a type of function which has been extensively used in various areas of economics. In this sense, this paper provides a theoretical foundation for the Cobb-Douglas functional form.

The analysis in this paper provides suggestions for new avenues of research on Cobb-Douglas production functions. As mentioned, the Cobb-Douglas form is given by $Y = AK^\alpha L^\beta$, where A represents the level of productivity of a firm, and α and β are positive parameters. The first avenue for further research concerns the values of α and β . In economics, it is important to know whether the sum of these two parameters equals unity or not. For example, Ref. [45] found that the sum of the two is close to unity in some countries but less than unity in others. The second potential research avenue concerns where the tail exponent of Y comes from. The Cobb-Douglas form shown above implies that it should come from the exponent of K , the exponent of L , or the exponent of A . Business persons often argue that the key to achieving high sales growth is high productivity growth, implying that the upper tail of Y should stem from the upper tail of A . However, Ref. [46] has shown that the power-law exponent of the productivity distribution in a country tends to be greater than the power law exponent of the sales distribution in that country, indicating that the upper tail of the productivity distribution is less heavy than that of the sales distribution. In a related context, Refs. [47, 48] examined the distribution of labour productivity for Japanese firms. Investigating in more detail how the fat tail of sales distributions is related to the tails of the distributions of productivity and other firm variables is a task we hope to address in the future.

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